

**PHY 102: DYNAMICS AND ELASTICITY**

**Chapter:2**  
**Oscillations**

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• 1

***Contents***

- **Simple Harmonic Motion revision**
- **Displacement, velocity and acceleration in SHM**
- **Energy in SHM**
- **Damped harmonic motion**
- **Forced Oscillations**
- **Resonance**

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• 2

### Simple Harmonic Motion

Object (eg mass on a spring, pendulum bob) experiences restoring force  $F$ , directed towards the equilibrium position, proportional in magnitude to the displacement from equilibrium:

$$F = -kx$$

$$m \frac{d^2 x}{dt^2} = -kx$$

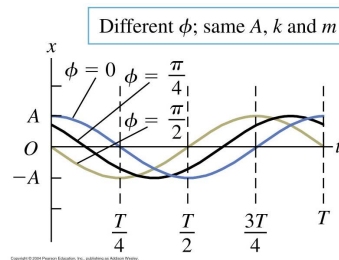
$$\frac{d^2 x}{dt^2} = -\omega^2 x$$

$$\omega = \sqrt{\frac{k}{m}}$$

Solution:

$$\omega =$$

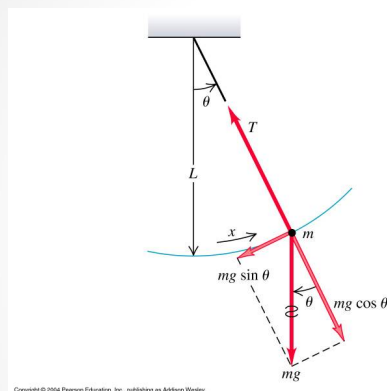
$x(t) =$



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3

### Example: Simple Pendulum (small amplitude)

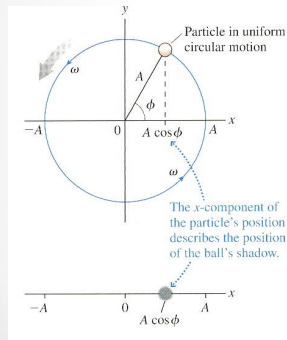
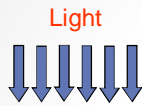


(NOT SHM for large amplitude)

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4

### SHM and Circular motion



Displacement of oscillating object = projection on x-axis of object undergoing circular motion

$$y(t) = A \cos \theta$$

For rotational motion with angular frequency  $\omega$ , displacement at time t:

$$y(t) = A \cos (\omega t + \varphi)$$

$\varphi$  = angular displacement at t=0 (phase constant)  
 A = amplitude of oscillation (= radius of circle)

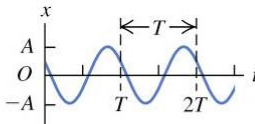
### Velocity and acceleration in SHM

Displacement :  $x(t) = A \cos(\omega t + \varphi)$

Velocity :  $v(t) = \frac{dx}{dt} =$

Acceleration :  $a(t) = \frac{d^2x}{dt^2} =$

### Velocity and acceleration in SHM

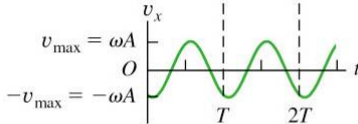


(a) Displacement

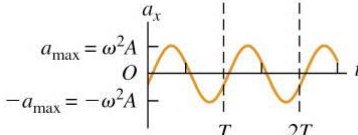
Displacement :  $x(t) = A \cos(\omega t + \phi)$

Velocity :  $v(t) = \frac{dx}{dt} = -\omega A \sin(\omega t + \phi)$

Acceleration :  $a(t) = \frac{d^2x}{dt^2} = -\omega^2 A \cos(\omega t + \phi)$



(b) Velocity



(c) Acceleration

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### Energy in Simple Harmonic Motion

Potential energy:

Work done to stretch spring by an amount  $dx = Fdx = -kxdx$

Total work done to stretch spring to displacement  $x$ :

$W = \text{stored potential energy} =$

So, at any time  $t$ , the potential energy of the oscillator is given by:

$PE =$

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### Energy in Simple Harmonic Motion

#### Kinetic Energy:

At any time t, kinetic energy given by:

$$KE = \frac{1}{2}mv^2 = \frac{1}{2}m\left(\frac{dx}{dt}\right)^2 =$$

Total Energy at time t = KE + PE:

$$E =$$

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9

### Energy in Simple Harmonic Motion

#### Conclusions

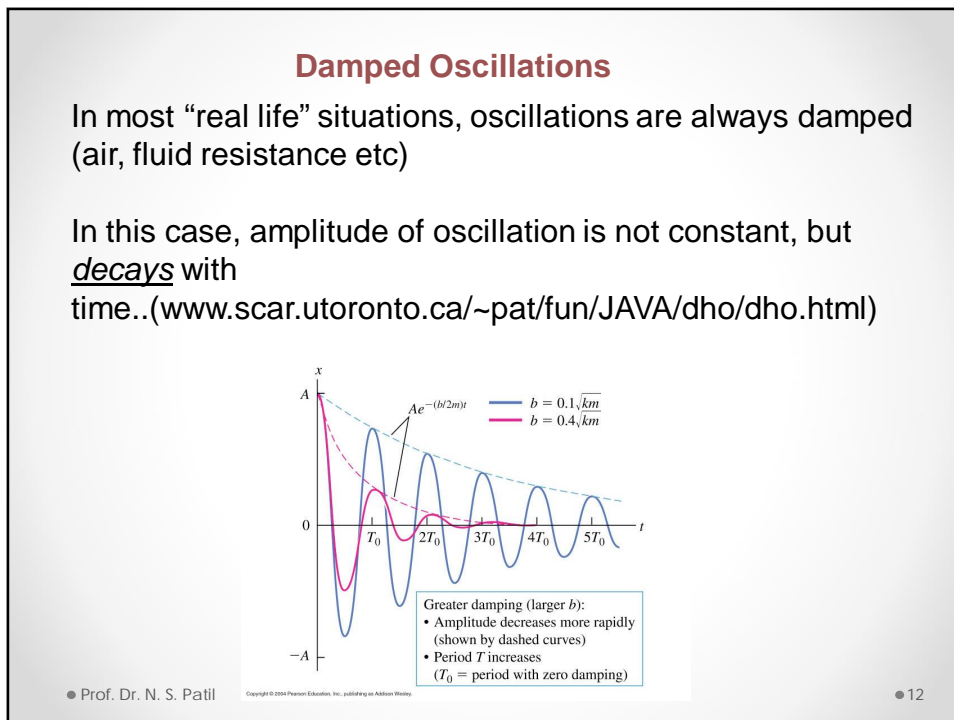
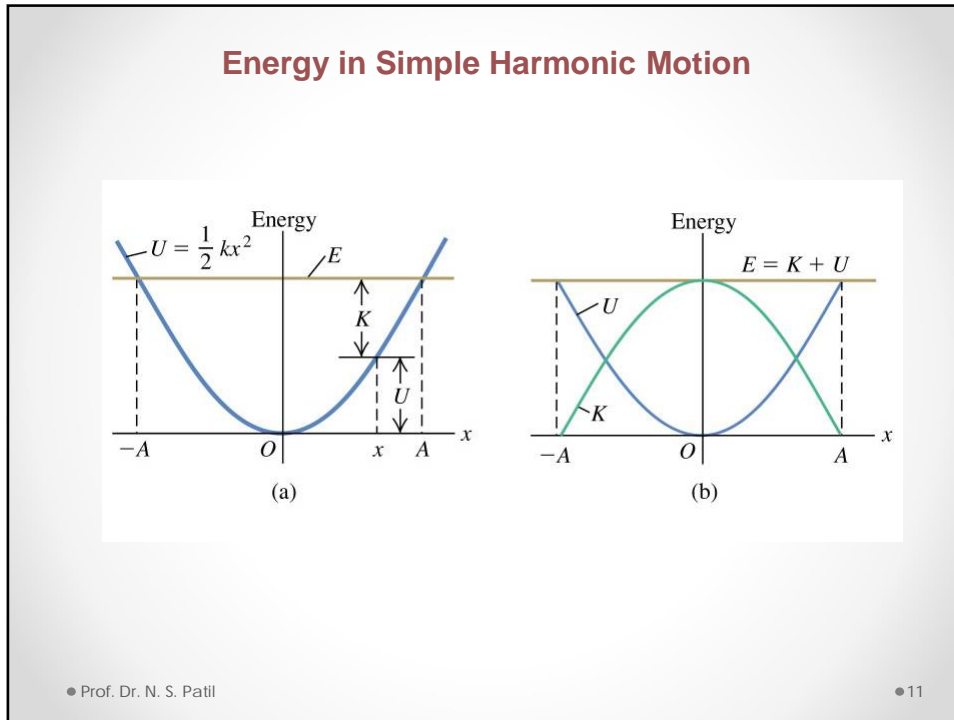
Total energy in SHM is constant

$$E = \frac{1}{2}m\omega^2A^2 = \frac{1}{2}kA^2$$

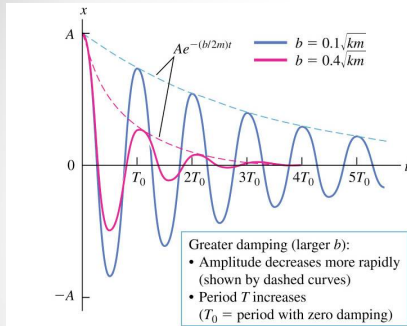
Throughout oscillation, KE continually being transformed into PE and vice versa, but **TOTAL ENERGY remains constant**

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10



### Damped Oscillations



For damped oscillations, simplest case is when the damping force is proportional to the **velocity** of the oscillating object

In this case, amplitude decays exponentially:

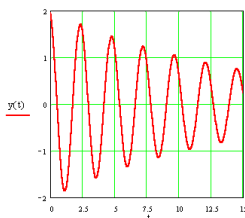
$$x(t) = Ae^{-(b/2m)t} \cos(\omega't + \phi)$$

Equation of motion:  $m \frac{d^2x}{dt^2} = -kx - b \frac{dx}{dt}$

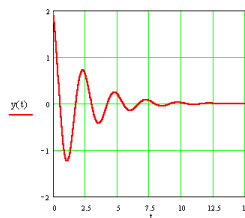
### Damped Oscillations

NB: in addition to time dependent amplitude, the damped oscillator also has modified frequency:

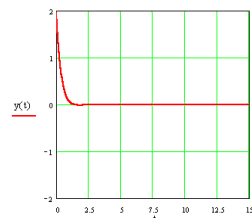
$$\omega' = \sqrt{\left(\frac{k}{m} - \frac{b^2}{4m^2}\right)} = \sqrt{\left(\omega_0^2 - \frac{b^2}{4m^2}\right)}$$



Light Damping (small  $b/m$ )



Heavy Damping (large  $b/m$ )



Critical Damping

$$\frac{k}{m} = \frac{b^2}{4m^2}$$

### Forced Oscillations & Resonance

If we apply a periodically varying driving force to an oscillator (rather than just leaving it to vibrate on its own) we have a **FORCED OSCILLATION**

Free Oscillation with damping:

$$m \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + kx = 0$$

$$\text{Amplitude} = A_0 e^{-(b/2m)t}$$

$$\text{Frequency } \omega' = \sqrt{\left(\frac{k}{m} - \frac{b^2}{4m^2}\right)} = \sqrt{\left(\omega_0^2 - \frac{b^2}{4m^2}\right)}$$

Forced Oscillation with damping:

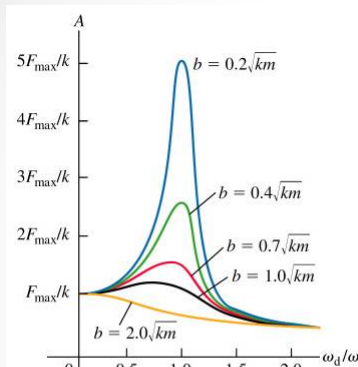
$$m \frac{d^2 x}{dt^2} + b \frac{dx}{dt} + kx = F_0 \cos \omega_D t$$

$$\text{Amplitude} = \frac{F_0}{\sqrt{\left(k - m\omega_D^2\right)^2 + b^2\omega_D^2}}$$

**MAXIMUM AMPLITUDE WHEN DENOMINATOR MINIMISED:**  
 $k = m\omega_D^2$  ie when driving frequency = natural frequency of the **UNDAMPED** oscillator

$$\omega_D = \omega_0 = \sqrt{\frac{k}{m}}$$

### Forced Oscillations & Resonance



Greater damping (larger  $b$ ):

- Peak becomes broader
- Peak becomes less sharp
- Peak shifts toward lower frequencies

If  $b > \sqrt{2km}$ , peak disappears completely

When driving frequency = natural frequency of oscillator, amplitude is maximum.

We say the system is in **RESONANCE**

“Sharpness” of resonance peak described by **quality factor (Q)**

High Q = sharp resonance

Damping reduces Q





**Thank you**